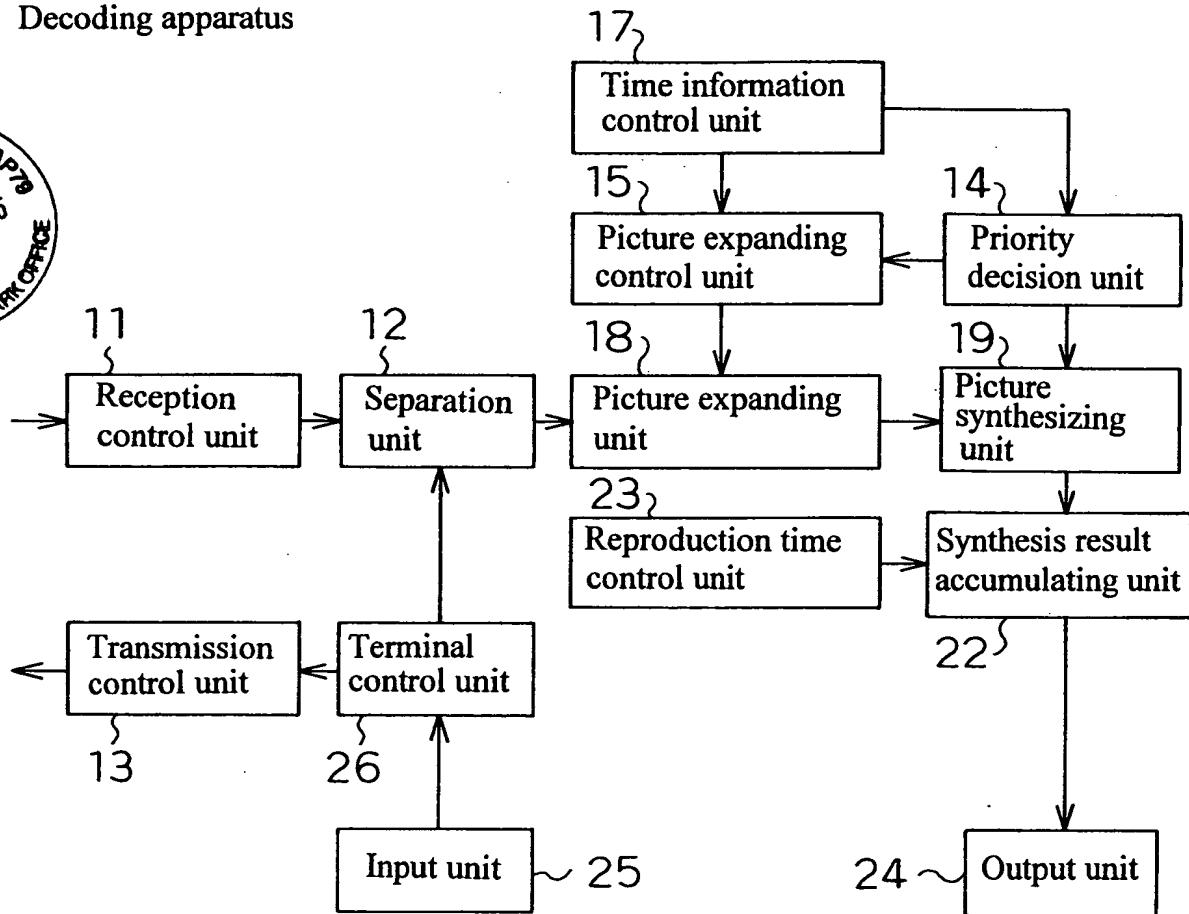


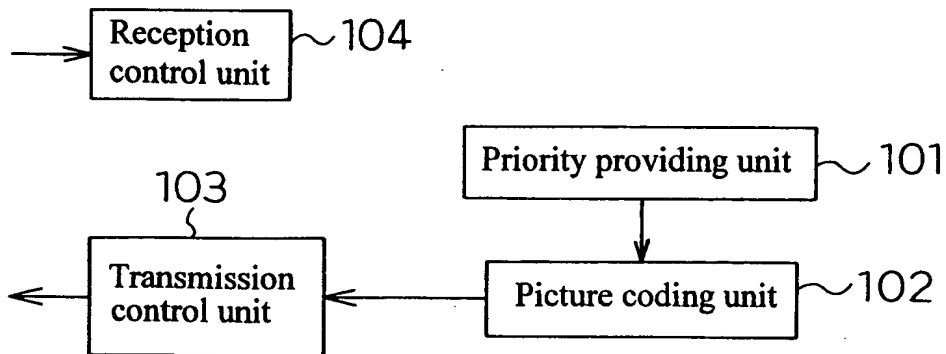
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Fig. 1

Decoding apparatus

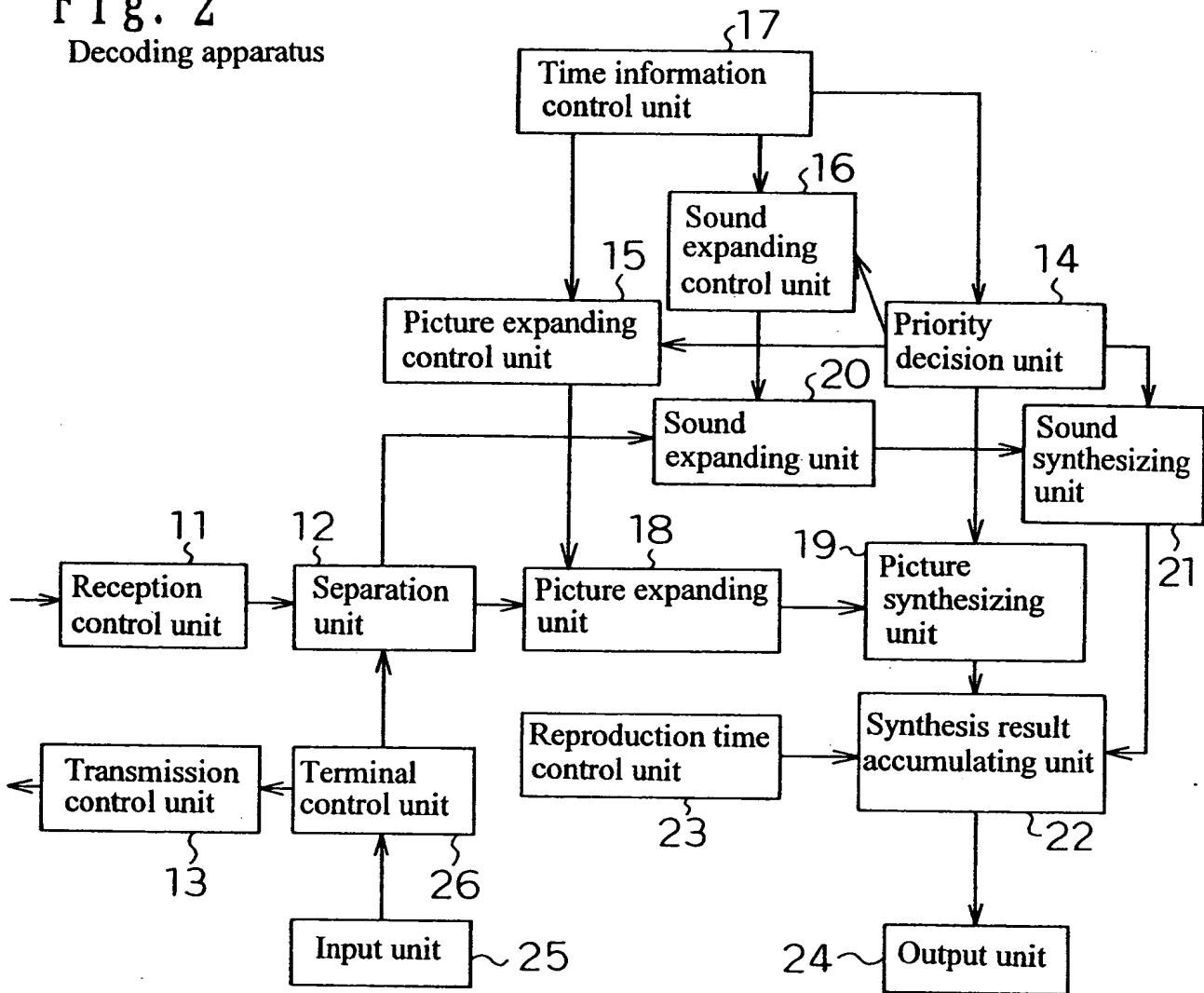


Coding apparatus



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Fig. 2  
 Decoding apparatus



Coding apparatus

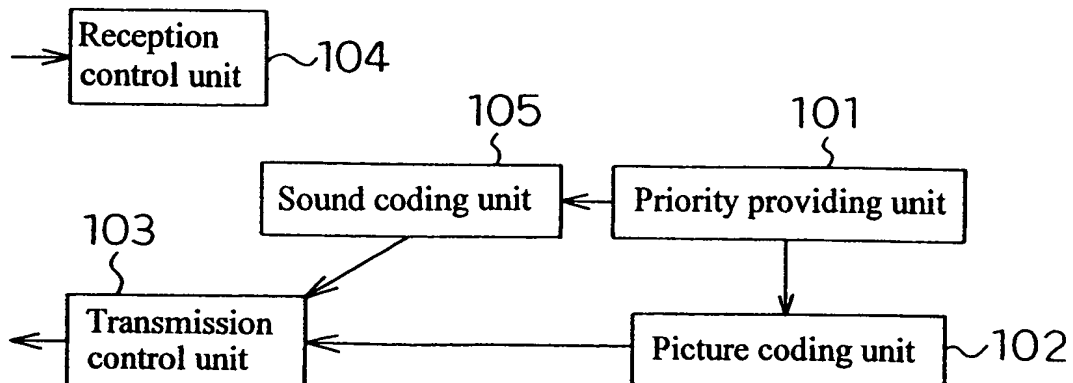


Fig. 3 (a)

All multiplexed format

Header information	Priority for defining reproduction sequence	Priority for defining processing when overloaded	Picture data 1	Sound data 1	-----	Picture data N	Sound data N
--------------------	---	--	----------------	--------------	-------	----------------	--------------

Information showing display sequence

\* The information describing the relation between pictures or between sounds may be described in the header information.

Fig. 3 (b)

Multiplexed in individual media, and transmitted from respective communication ports

Header information	Priority for defining reproduction sequence	Priority for defining processing when overloaded	Control information				
Header information	Picture data 1	-----	Picture data row				
Header information	Sound data 1	-----	Sound data row				

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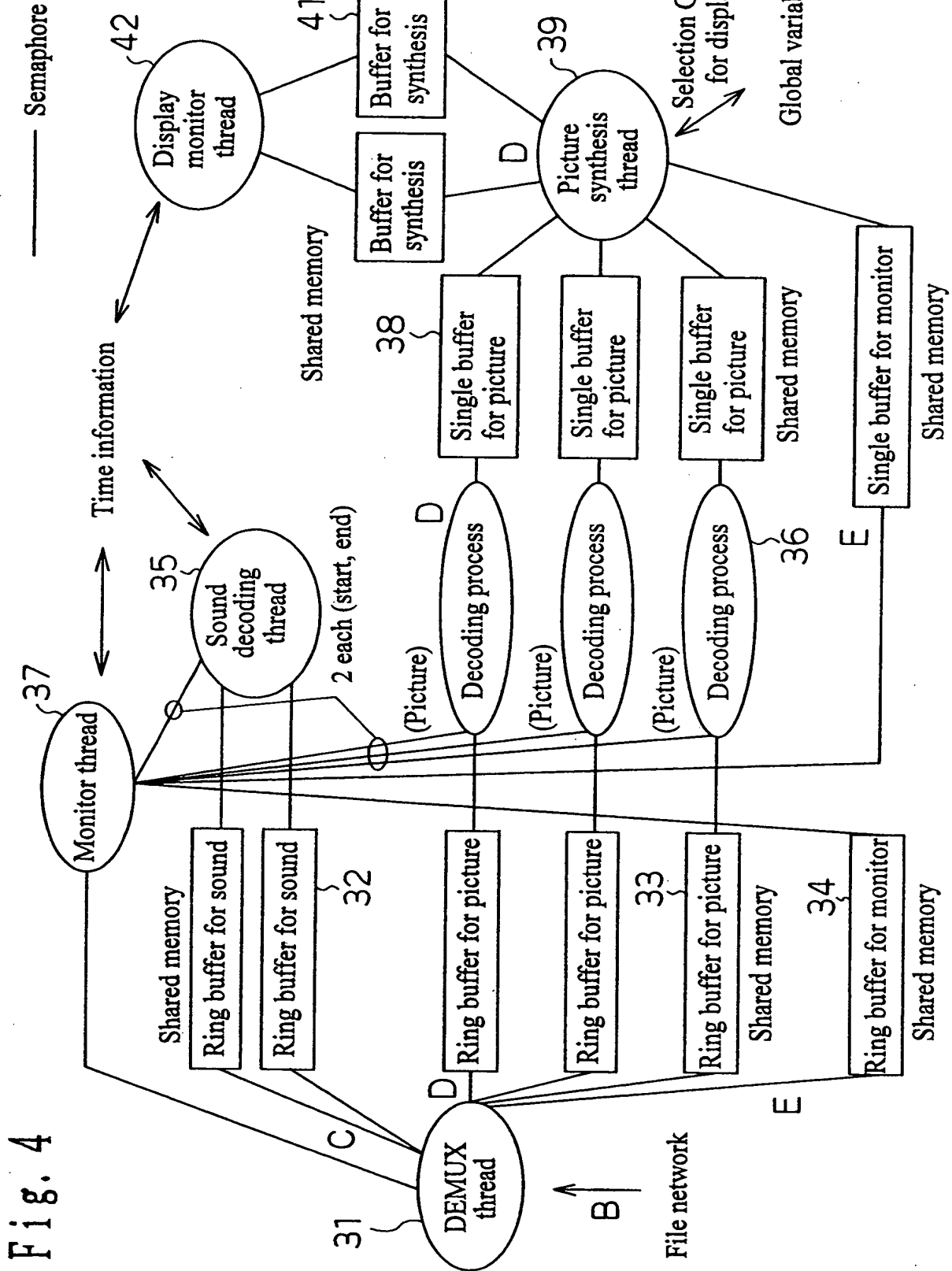


Fig. 5

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B.

```
struct shm_tspkt {
    data_byte      188byte      Packet data
}
```

C.

```
struct shm_apkt {
    DWORD  sync_code      32bit  Packet synchronous code
    WORD   pts            16bit  Display time
    WORD   frame_length   16bit  Frame length
    BYTE   data_byte      Nbyte  Sound data
                                   (N=frame_length)
}
```

D.

```
struct shm_vpkt {
    DWORD  sync_code      32bit  Packet synchronous code
    BYTE   temporal_reference 8bit  Frame number
    WORD   frame_length   16bit  Frame length
    BYTE   data_byte      Nbyte  Picture data
                                   (N=frame_length)
}
```

E.

```
struct shm_kanshi_info {
    WORD  pts            16bit  Display time
    BYTE  number_of_object 8bit  No. of objects
    for (i=0: i<number_of_object:i++) {
        BYTE  object_id      8bit  ID
        BYTE  temporal_reference 8bit  Frame number
        BYTE  object_priority 4bit  Priority (*1)
        reserved      2bit
        IPB_flag      2bit  Frame type
        WORD  horizontal_offset 10bit Display position, horizontal
        WORD  vertical_offset  10bit Display position, vertical
        BYTE  layer            4bit  Layer
    }
}
```

(\*1) Bits are assigned from the highest position sequentially by 4 bits  
(object\_priority), 2 bits, 2 bits (IPB\_flag)

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## Fig. 6

DEMUX thread

```
void demux ( )  
{  
    Shared memory (ring), semaphore generation process: for output  
        (2 for sound, 3 for picture, 1 for monitor table)  
    Semaphore generation for monitor thread control (one)  
    BOOL flag = TRUE: // State of ring buffer  
  
    while(1) {  
        if(flag) Reading from file or network - (5-1)  
  
        if(flag)  
            Analysis of 188-byte packet data, setting in specified structure - (5-2)  
            (decomposed into information of sound, picture, monitor table)  
  
        // Exclusive control of ring buffer by semaphore  
        if (Able to write in ring buffer?) {  
            Write into ring buffer (from earlier object ID, write sequentially - (5-3)  
                into shared memory of earlier buffer number)  
            Advance write pointer of written buffer - (5-4)  
            flag=TRUE:  
        }else  
            flag=FALSE: // Prevent overflow of ring buffer  
  
        if(flag)  
            After writing information of pictures and sounds for one monitor - (5-5)  
            table, advance the counter of semaphore for monitor thread control  
    }  
}
```

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Fig. 7

Monitor thread

```
void Watch Process ( )
{
    BYTE disp_TR[i]: // Picture serial number (shared memory)
    BOOL skip_flag[i]: // Skip flag to which decoding process refers
                        (shared memory)

    Shared memory (ring buffer: monitor table 1)
    Semaphore open: used by determining priority of processing
    Shared memory (single buffer: monitor table 1)
    Semaphore generation: transfer to synthesis side
    Generation of semaphore for process monitor
    Semaphore open for monitor thread control (one)

    Start of picture decoding process
    Confirm start of process
    while {skip_flag[i]=FALSE: // Not skipped }

    while(1)
    {
        Reading of monitor table (read pointer update, from DEMUX)
        Check of object priority - (6-1) - (6-2)
        Writing of monitor table (to synthesis side) - (6-3)
        Wait for creation of data for one monitor table from DEMUX - (6-4)

        From highest priority
        {
            disp_TR[i]=TR: - (6-5)
            if ( Present time > display time (pts) ) { - (6-6)
                Not skipped if I frame
                skip_flag[i]=FALSE
            }else{
                P, B frames are skipped
                skip_flag[i]=TRUE
            }
            Release of semaphore of corresponding process - (6-7)
            Wait for release of semaphore of corresponding process - (6-8)
            (process completion check)
        }
    }
}
```

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## Fig. 8

Decoding process

```
void main(int argc, char *argv[ ] )  
{
```

Value received from main process :

Shared memory to be opened, name of semaphore

Shared memory (ring), open processing of semaphore: for input (from MUX)

Shared memory (single), open processing of semaphore: for output (to synthesis  
side)

```
while(1) {  
    Monitor thread waits for release of semaphore                - (7-1)  
  
    Input picture state check:                                    - (7-2)  
        Picture serial number (TR), skip input frame?  
  
    Wait for picture data to be decoded                          - (7-3)  
  
    Is TR present in shared memory? {                            - (7-4)  
        Skip decoding if not present  
        Advance read pointer for ring buffer (for input)  
    }  
  
    if (Skip one input frame) {  
        Decoding process                                        - (7-5)  
        Advance read pointer for ring buffer (for input)  
    }  
  
    Output of decoding result (*1)                              - (7-6)  
    Release semaphore to monitor thread (process end notice)    - (7-7)  
}
```

(\*1) When skipping input frame process, send signal to main process without  
decoding process and output of decoding result



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## Fig. 9

Picture synthesis thread

```

void Watch Sync ( )
{
    Shared memory (single), semaphore generation process: for input (from decoder)
    Shared memory (single), semaphore generation process: for input (from monitor
                                                                    thread)
    Shared memory (single), semaphore generation process: for output (to display
                                                                    monitor: 2)
    BOOL flag=TRUE:

    while(1) {
        Wait for monitor table from monitor thread                - (8-1)
        Check priority order of object                            - (8-2)

        From highest priority order {                             - (8-3)
            Wait for picture of decoding result (accumulated in shared memory)
            // Totally black if empty
        }
        Synthesis of image adjusting to display position          - (8-4)

        // Double buffer
        if (flag) {                                                - (8-5)
            Write synthesis result into shared memory (to display monitor) #1
            flag=FALSE:
        } else {
            Write synthesis result into shared memory (to display monitor) #2
            flag=TRUE:
        }
    }
}

```

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Fig. 10

Display monitor thread

```
void Watch Disp ( )
{
    Shared memory (single), open processing of semaphore: for input
                                     (from synthesis thread: 2)
    BOOL  flag = TRUE:

    while(1)
    {
        // Double buffer
        if (flag) {
            Wait for synthesis picture from shared memory (from synthesis thread)#1
            flag = FALSE:                                     - (9-1)
        } else {
            Wait for synthesis picture from shared memory (from synthesis thread)#2
            flag = TRUE:
        }

        if (Initial display) {
            Acquire display start time from timer                - (9-2)
        }
        Sleep (pts-nowtime):                                     - (9-3)
        Display of synthesis picture
    }
}
```

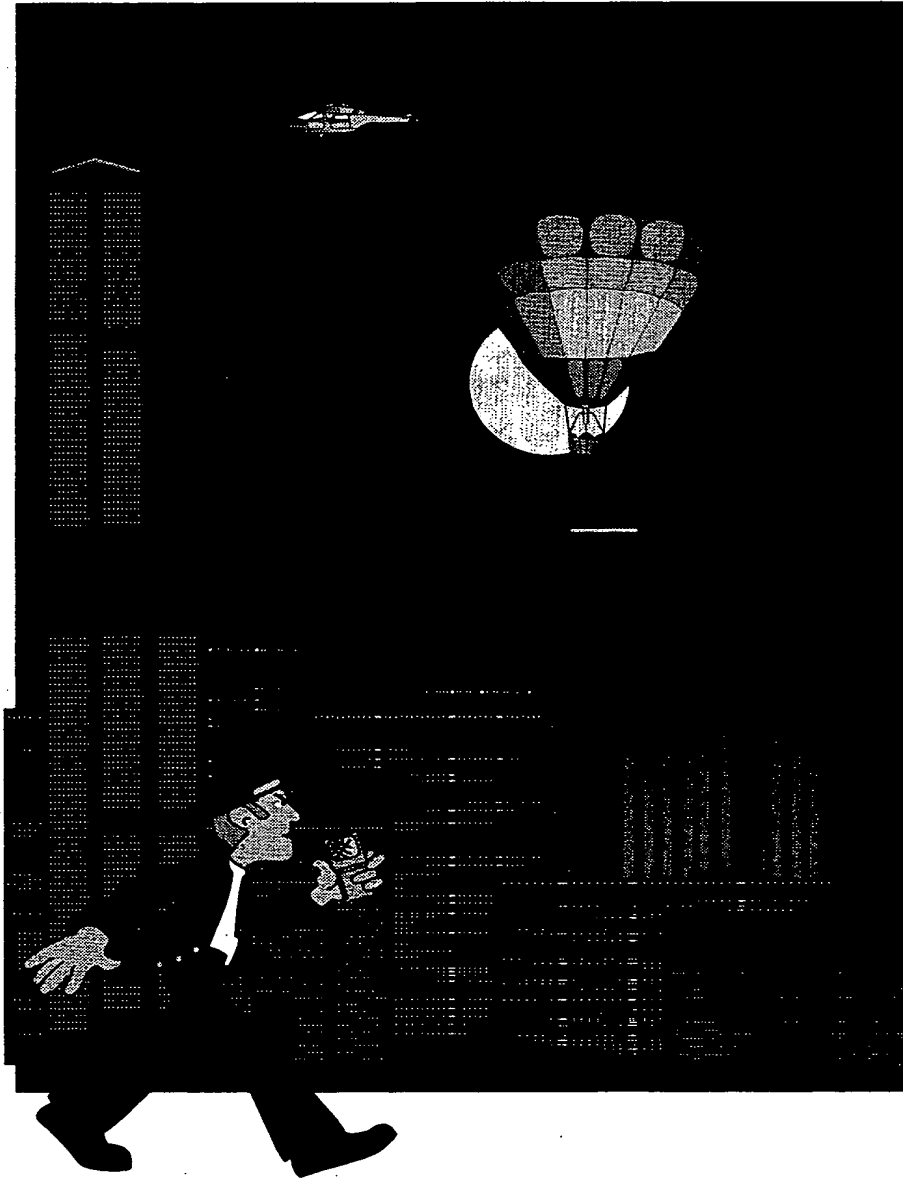
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Fig. 11

Three-dimensional picture  
(foreground: helicopter)

Three-dimensional picture  
(foreground: balloon)

Background picture  
(night sky)



Foreground picture  
(building)  
Synthesis ratio: 0.5

Foreground picture (man)

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Fig. 12 (a)

System of hardware base

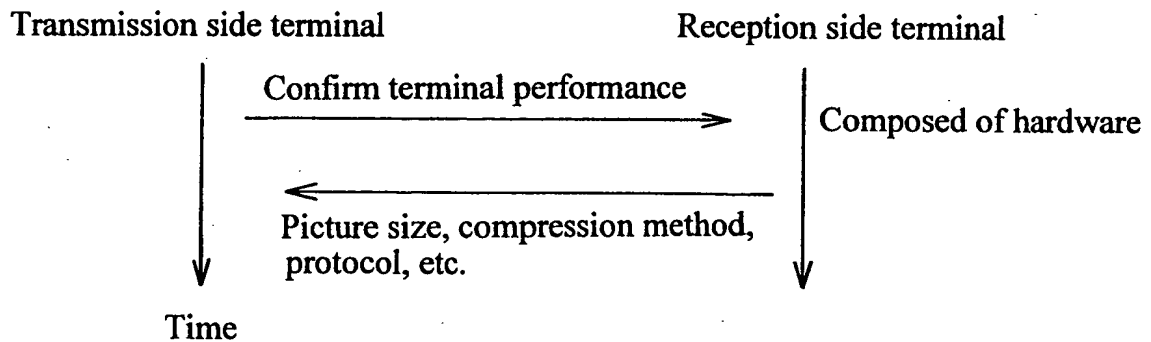
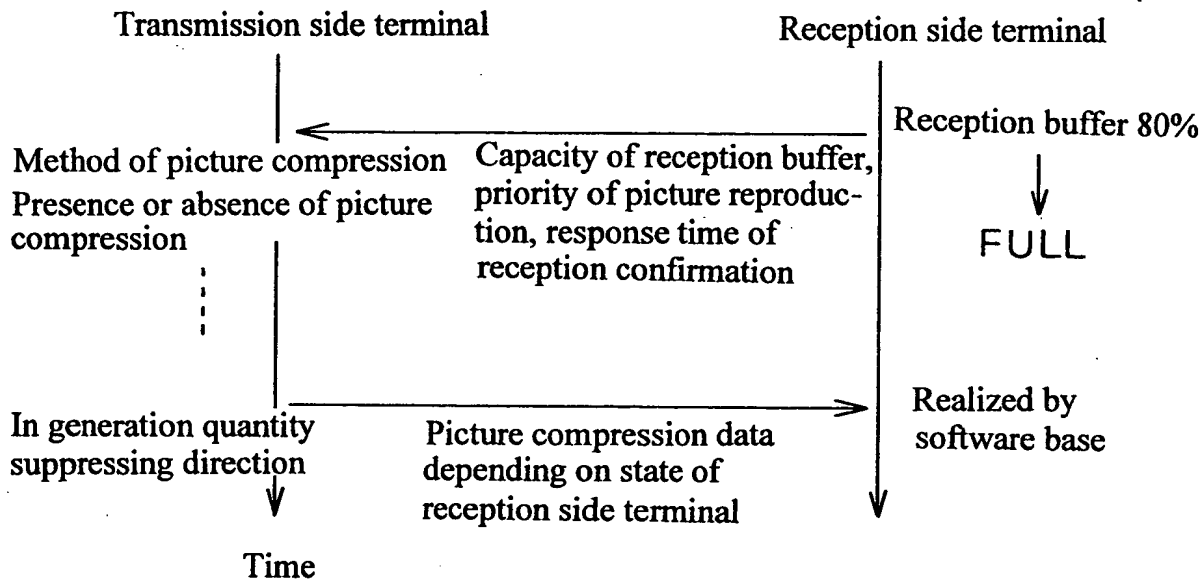


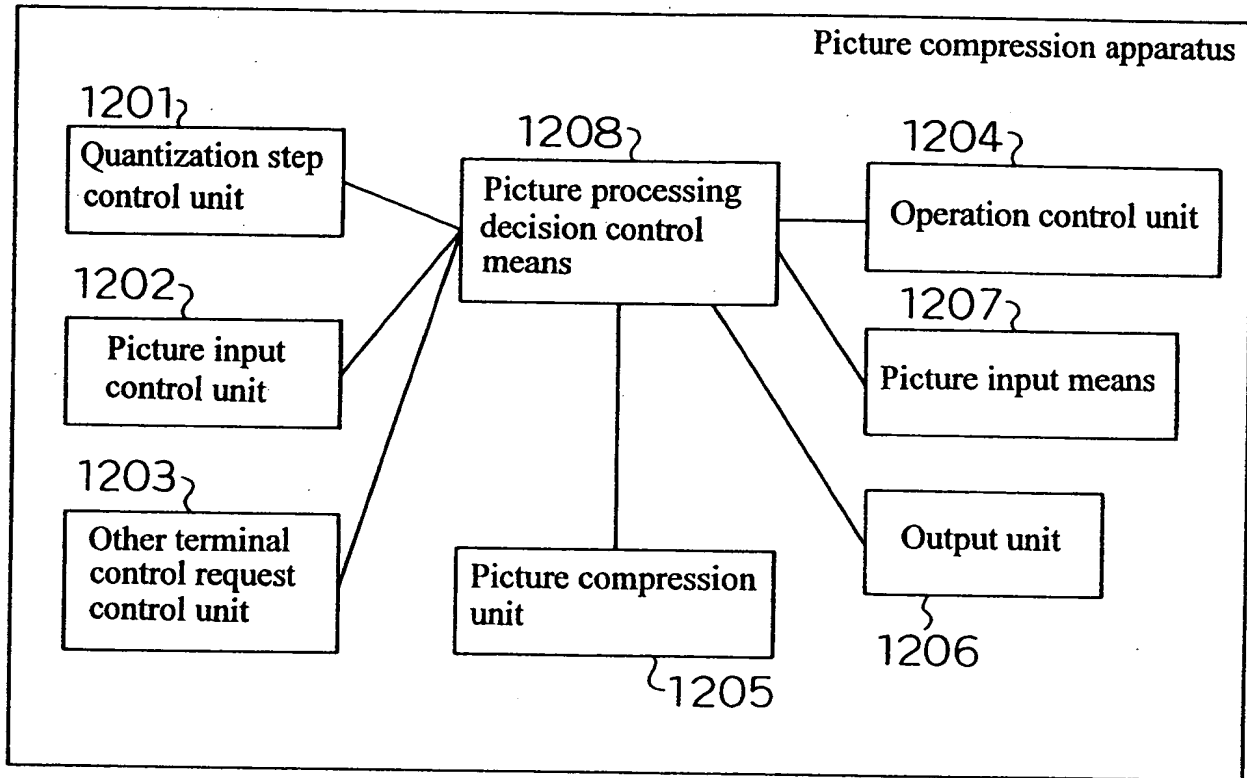
Fig. 12 (b)

System of software base



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Fig. 13



\* Sound compression apparatus can be set similarly

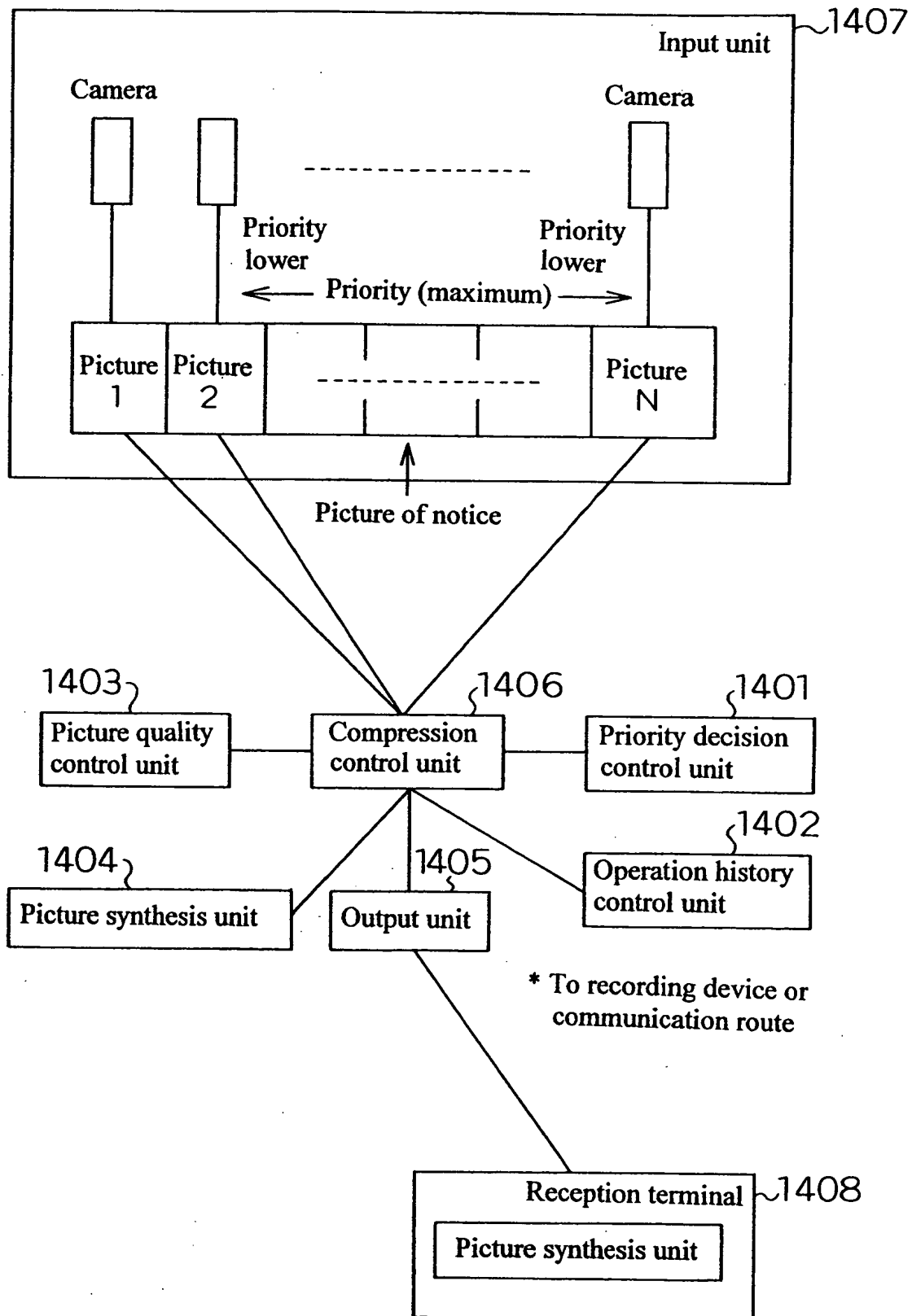
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Fig. 14

Picture size	Camera control	Other terminal control request	Quantization step
QC I F	Pan	Buffer over	16
C I F	None	None	16
QC I F	None	None	18
QC I F	Tilt	None	14
⋮	⋮	⋮	⋮

Fig. 15

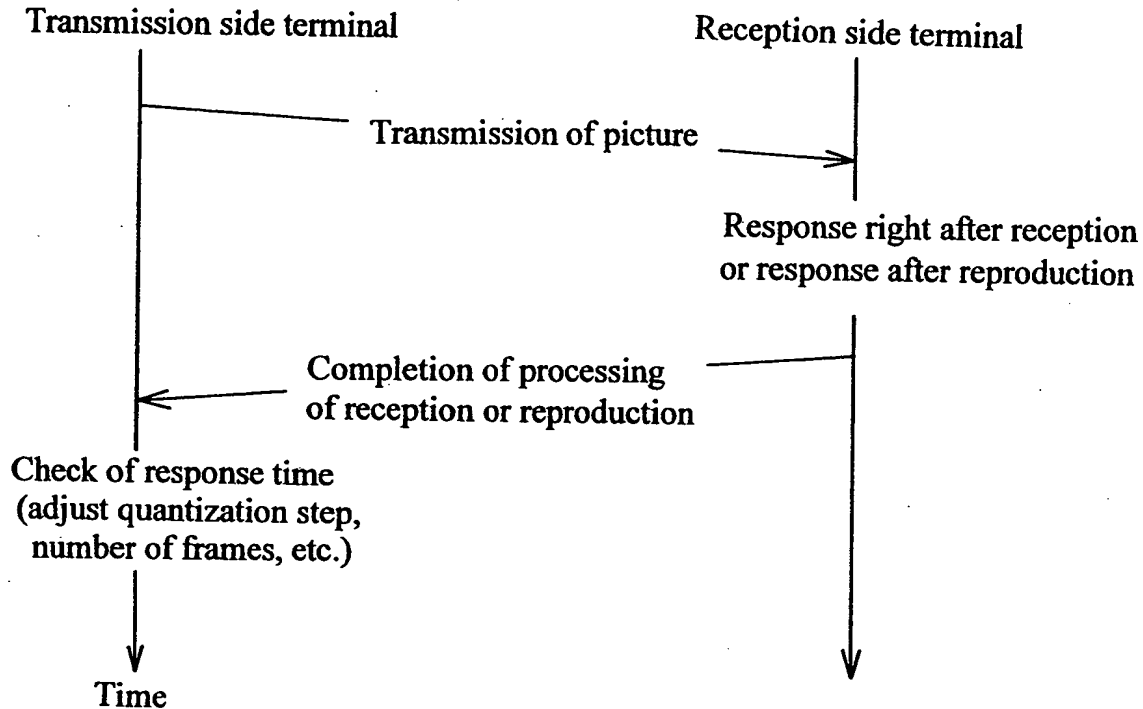
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Fig. 16

- Feedback relating to response between transmission terminal and reception terminal (case 1)



- Feedback of reproduction situation to transmission side terminal (case 2)

